$$S(v) = \begin{cases} 0 & \text{if } v = (i,0) \text{ for } 0 \le i \le |x|, \\ 0 & \text{if } v = (0,j) \text{ for } 0 \le j \le |y|, \end{cases}$$

$$S(v) = \begin{cases} 0, & \text{if } v = (0,j) \text{ for } 0 \le j \le |y|, \\ S((i-1,j-1)) + score(x[i],y[j]), & \text{if } v = (i,j) \text{ for } \left\{ 1 \le i \le |x|, \\ 1 \le j \le |y| \right\}, \end{cases}$$

$$\max_{0 \le i \le |x| \\ 0 \le j \le |y|} \left\{ S((i,j)) \right\} & \text{if } v = v_{\bullet}.$$

Table 5.4: Smith-Waterman algorithm for local alignment with general gap costs

the framework of general gap costs. We shall see, however, that a quadratic-time algorithm (O(mn) time) exists; the idea is due to Gotoh (1982). We explain it for global alignment; the required modifications for the other alignment types are easy.

Recall that S((i,j)) is the alignment score for the two prefixes x[1...i] and y[1...j]. In general, such a prefix alignment can end with a match/mismatch, a deletion, or an insertion. In the indel case, either the gap is of length $\ell = 1$, in which case its cost is g(1) = d, or its length is $\ell > 1$, in which case its cost can recursively be computed as $g(\ell) = g(\ell - 1) + e$.

The main idea is to additionally keep track of (i.e., to tabulate) the *state* of the last alignment column. In order to put this idea into an algorithm, we define the following additional two matrices:

$$V\big((i,j)\big) := \max \left\{ score(A) \, \middle| \, \begin{array}{l} A \text{ is an alignment of the prefixes } x[1\ldots i] \text{ and } y[1\ldots j] \\ \text{that ends with a gap character in } y \end{array} \right\},$$

$$H\big((i,j)\big) := \max \left\{ score(A) \, \middle| \begin{array}{l} A \text{ is an alignment of the prefixes } x[1\ldots i] \text{ and } y[1\ldots j] \\ \text{that ends with a gap character in } x \end{array} \right\}.$$

Then

$$S \big((i,j) \big) = \max \big\{ S \big((i-1,j-1) \big) + score(x[i],y[j]), \, V \big((i,j) \big), \, H \big((i,j) \big) \big\} \,,$$

which gives us a method to compute the alignment matrix S, given the matrices V and H. It remains to explain how V and H can be computed efficiently. Consider the case of $V\big((i,j)\big)$: A gap of length ℓ ending at position (i,j) is either a gap of length $\ell=1$, in which case we can easily compute $V\big((i,j)\big)$ as $V\big((i,j)\big)=S\big((i-1,j)\big)-d$. Or, it is a gap of length $\ell>1$, in which case it is an extension of the best scoring vertical gap ending at position (i-1,j), $V\big((i,j)\big)=V\big((i-1,j)\big)-e$. Together, we see that for $1\leq i\leq m$ and $0\leq j\leq n$,

$$V\big((i,j)\big) = \max \big\{ S\big((i-1,j)\big) - d, \ V\big((i-1,j)\big) - e \big\}.$$

Similarly, for horizontal gaps we obtain for $0 \le i \le m$ and $1 \le j \le n$,

$$H((i,j)) = \max \{S((i,j-1)) - d, H((i,j-1)) - e\}.$$

The border elements are initialized in such a way that they do not contribute to the maximum in the first row or column, for example:

$$V((0,j)) = H((i,0)) = -\infty.$$