

Topics of today:

1. Small Parsimony / Big Parsimony
2. Fitch's algorithm
3. Small Parsimony with SCJ
4. Quiz-review

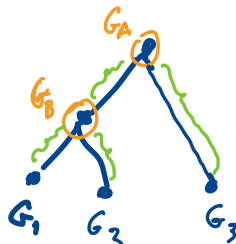
Small (and big) parsimony problems

$d_M(G_1, G_2)$: distance between two genomes under some model M

Binary tree T $\begin{cases} \text{topology of } T \text{ is known} \\ \text{each leaf } u \text{ of } T \text{ corresponds to a given genome } G_u \end{cases}$

Function \mathcal{A} : assigns a genome $\mathcal{A}(u)$ to each node u of T
(if u is a leaf of T , then $\mathcal{A}(u) = G_u$)

Weight $w(uv)$ of a branch uv of T under $\begin{cases} \text{assignment } \mathcal{A} \\ \text{model } M \end{cases}$: $w(uv) = d_M(\mathcal{A}(u), \mathcal{A}(v))$



Small parsimony problem under the model M :

Find an assignment \mathcal{A} that minimizes the total branch weight of T :

$$\mathcal{W}(T) = \min_{\mathcal{A} \in \mathfrak{A}} \sum_{uv \in E(T)} d_M(\mathcal{A}(u), \mathcal{A}(v))$$

Big parsimony problem under the model M :

Given a set of k genomes G_1, G_2, \dots, G_k ,

find $\begin{cases} \text{tree } T \text{ whose } k \text{ leaves are in one-to-one correspondence with the genomes } G_1, G_2, \dots, G_k \\ \text{assignment } \mathcal{A} \text{ of genomes to the nodes of } T \end{cases}$
minimizing the total branch weight $\mathcal{W}(T)$

Small parsimony with Fitch's algorithm

General model:

$$\begin{cases} \text{binary rooted tree } T, \text{ with } n \text{ nodes} \\ \text{genomes are represented by sequences of a fixed length } \ell, \text{ over a finite alphabet } \Sigma \text{ (with } |\Sigma| = m) \\ \text{hamming distance (hd) gives the weight of the branches} \end{cases}$$

Assuming positions being mutually independent, the problem can be solved for each position separately:

The algorithm determines an optimal value for each position p of each node v , denoted by $s_v[p]$

Bottom-up phase: defines set $B(v, p)$ of possible values for each $s_v[p]$, based on v 's children x_1 and x_2

$$\begin{cases} \text{if } v \text{ is a leaf : } B(v, p) = \{s_v[p]\} \\ \text{else } \begin{cases} \text{compute } B(v, p) = B(x_1, p) \cap B(x_2, p) \\ \text{if } B(v, p) = \emptyset : B(v, p) = B(x_1, p) \cup B(x_2, p) \end{cases} \end{cases}$$

Complexity: $O(mn)$ (bottom-up traversal takes $O(n)$, computation of each node takes $O(m)$)

Top-down phase: defines final value $s_v[p]$, based on set $B(v, p)$ and v 's parent u

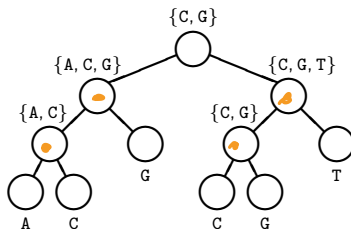
$$\begin{cases} \text{if } v \text{ has a parent } u \text{ and } s_u[p] \in B(v, p) : s_v[p] = s_u[p] \\ \text{otherwise (including the root), arbitrarily assign any value from } B(v, p) \text{ to } s_v[p] \end{cases}$$

Complexity: $O(mn)$ (top-down traversal takes $O(n)$, computation of each node takes $O(m)$)

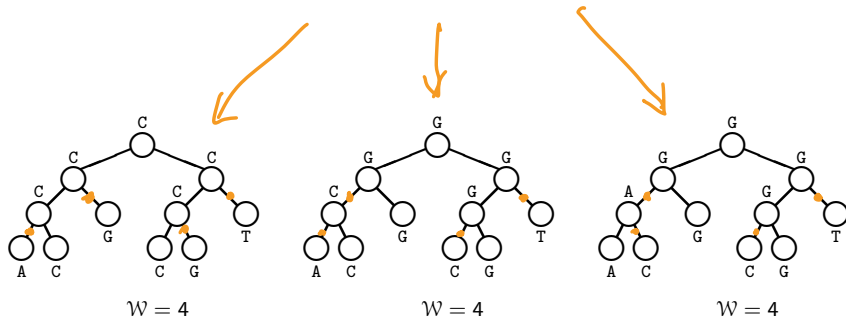
Total complexity: $O(mn)$ per position; with ℓ positions: $O(\ell mn)$

Small parsimony with Fitch's algorithm

Bottom-up phase:



Top-down phase:



Small parsimony under SCJ with Fitch's algorithm

$$\mathcal{F} = \{1, 2\}$$

$$\hat{\alpha}(\mathcal{F}) = \{1^h 1^t, 1^h 2^h, 1^h 2^t, 1^t 2^h, 1^t 2^t, 2^h 2^t\}$$

$$\left\{ \begin{array}{l} \text{set of gene families } \mathcal{F} \\ \text{set of extremities } \xi(\mathcal{F}) = \{f^t : f \in \mathcal{F}\} \cup \{f^h : f \in \mathcal{F}\} \quad (|\xi(\mathcal{F})| = 2|\mathcal{F}|) \\ \text{set of all possible adjacencies } \hat{\alpha}(\mathcal{F}) = \{\text{subsets of } \xi(\mathcal{F}) \text{ with size } 2\} \end{array} \right.$$

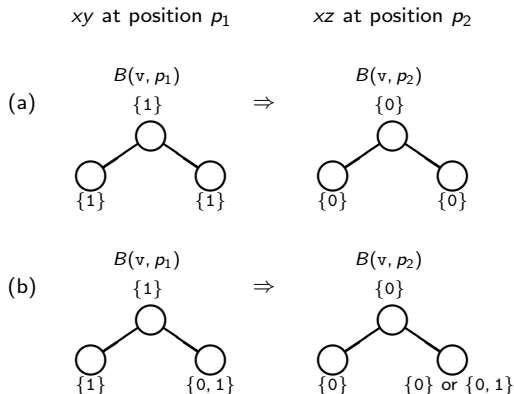
$$\Rightarrow |\hat{\alpha}(\mathcal{F})| = \binom{|\xi(\mathcal{F})|}{2} = \binom{2|\mathcal{F}|}{2} = \frac{2|\mathcal{F}|(2|\mathcal{F}|-1)}{2} = O(|\mathcal{F}|^2)$$

Note: $\hat{\alpha}(\mathcal{F})$ has many pairs of **conflicting adjacencies** xy, xz with $y \neq z$

$$\left\{ \begin{array}{l} \text{genome assigned to vertex } u \\ \text{represented by a sequence } s_u \text{ of length } \ell = |\hat{\alpha}(\mathcal{F})| \text{ over the binary alphabet } \{0, 1\} \\ \text{cannot contain conflicting adjacencies:} \\ \text{for each pair of conflicting adj. in } \hat{\alpha}(\mathcal{F}), \text{ at most one of the two can be set to 1 in } s_u \end{array} \right.$$

Small parsimony under SCJ with Fitch's algorithm

Possible bottom-up
scenarios involving
two conflicting adjacencies



Conflicts can be avoided by assigning the value 0 to each ambiguous position of the root genome:

$$r \text{ is the root of } T: \text{ for each position } p \text{ of } s_r \begin{cases} s_r[p] = 1 & \text{if } B(r, p) = \{1\} \\ s_r[p] = 0 & \text{otherwise} \end{cases}$$

It is easy to verify that: $d_{SCJ}(u, v) = \text{hd}(s_u, s_v)$

Close-related problems are NP-hard...

Small parsimony under breakpoint distance

Big parsimony under SCJ

References

Toward Defining the Course of Evolution: Minimum Change for a Specific Tree Topology

(Walter M. Fitch)

Systematic Zoology, vol. 20, pp. 406–416 (1971)

SCJ: A Breakpoint-Like Distance that Simplifies Several Rearrangement Problems

(Pedro Feijão and João Meidanis)

TCBB volume 8 Number: 5 (2011)

Quiz - Review

Inversion model 1

- 1 In the DCJ model any operation reconstructing a target adjacency is optimal, but the same is not true for the inversion model because...

A a target adjacency can be bad

B a target adjacency can be already present in the genome

☒ C reconstructing a target adjacency can be unsafe

1 2 3 ...
-1 2
1 ... 2 ...
1-2

- 2 A cycle is bad when...

A it cannot be sorted by inversions

B it interleaves another bad cycle

☒ C it contains only bad target adjacencies

- 4 A bad component can be fixed...

☒ A with a neutral inversion

B with a split inversion

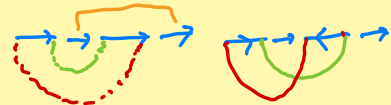
C with a safe inversion

- 3 Which data structure helps finding safe inversions?

A relational diagram

☒ B overlap graph

C component tree



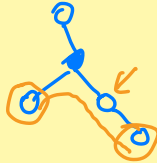
Inversion model 2

1 Each leaf of the component tree represents...

A a bad component

☒ B a hurdle

C a fortress



2 The cost of covering a component tree can be expressed in terms of...

A the number of bad nodes

B the length of the longest traversal of the tree

☒ C the number of leaves

3 Fixing a super hurdle with a neutral inversion

A is a good strategy

☒ B creates a new hurdle

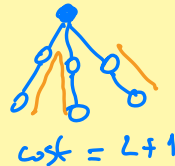
C destroys a good component

4 Merging two good (or trivial) components..

☒ A can merge bad components into a good one

B creates a new bad component

C is never recommended



DCJ-indel model 1

1 The indel-potential is defined as...

- A the number of runs in a component
- ☒ B the smallest number of runs that can be obtained after sorting with internal gaining DCJs
- C the number of indel-edges in a component

2 The indel-potential of a component depends on..

- ☒ A its number of runs
- B its number of indel-edges
- C its length

3 The number of runs in a cycle can be...

- ☒ A 0,1,2,4,6,8,...
- B any non-negative integer
- C any positive integer

4 The number of runs in a path can be...

- A 0,1,2,4,6,8,...
- ☒ B any non-negative integer 0,1,2,3,4,5,...
- C any positive integer 1,2,3,4,5,...

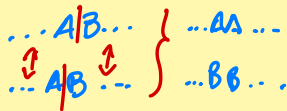
DCJ-indel model 2

- 1 A recombination can reduce the overall number of runs by at most...

A 1

B 2

C 3



- 2 A recombination can reduce the overall overall indel-potential by at most...

A 1

B 2

C 3

λ	λ
0	0
1	1
2	2
3	2
4	3
5	3

- 3 A recombination involving a cycle is...

A gaining

B neutral

Closing



- 4 A recombination involving a cycle can be...

A deducting

B) part of an optimal sorting sequence

if $\Delta_\lambda = -2$

C none of those

DCJ-indel model - Path recombinations

With respect to the endpoints:

$$A \text{---} B + B \text{---} B \left\{ \begin{array}{l} A \text{---} B + A \text{---} B \text{ (gaining)} \\ A \text{---} B + A \text{---} B \text{ (gaining)} \end{array} \right.$$

$$A \text{---} B + A \text{---} B \left\{ \begin{array}{l} \cancel{A \text{---} A + B \text{---} B \text{ (losing)}} \\ A \text{---} B + A \text{---} B \text{ (neutral)} \end{array} \right.$$

$$A \text{---} A + A \text{---} A \left\{ \begin{array}{l} A \text{---} A + A \text{---} A \text{ (neutral)} \\ A \text{---} A + A \text{---} A \text{ (neutral)} \end{array} \right.$$

With respect to the runs:

$$AB + AB \left\{ \begin{array}{l} B \text{---} B + \varepsilon \quad (\Delta_\lambda = -2) \\ AA + BB \quad (\Delta_\lambda = -2) \\ ABBA + \varepsilon \quad (\Delta_\lambda = -2) \end{array} \right.$$

$$A(B) + A \left\{ \begin{array}{l} AA + (B) \quad (\Delta_\lambda = -1) \\ AA(B) + \varepsilon \quad (\Delta_\lambda = -1) \end{array} \right.$$

$$(A)B + B \left\{ \begin{array}{l} (A) + BB \quad (\Delta_\lambda = -1) \\ (A)BB + \varepsilon \quad (\Delta_\lambda = -1) \end{array} \right.$$

$$\text{Deducting path recombinations: } \left\{ \begin{array}{l} \text{gaining with } \Delta_\lambda = -2 \\ \text{gaining with } \Delta_\lambda = -1 \\ \text{neutral with } \Delta_\lambda = -2 \end{array} \right.$$

DCJ-indel model - Path recombinations

Putting together (examples):

$$\begin{array}{c} AB_{AB} \\ \text{A-AB-B} \end{array} + \begin{array}{c} AB_{AB} \\ \text{A-AB-B} \end{array} = \begin{array}{c} AB_{AB} \\ \text{A-ABAB-B} \end{array} + \begin{array}{c} AB_{\epsilon} \\ \text{A-B} \end{array} \quad (\text{neutral, with } \Delta_{\lambda} = -1)$$

$$\begin{array}{c} AB_{AB} \\ \text{A-AB-B} \end{array} + \begin{array}{c} AB_{AB} \\ \text{A-AB-B} \end{array} = \begin{array}{c} AB_{AB} \\ \text{A-ABAB-B} \end{array} + \begin{array}{c} AB_{\epsilon} \\ \text{A-B} \end{array} \quad (\text{neutral, with } \Delta_{\lambda} = -1)$$

$$\begin{array}{c} AB_{AB} \\ \text{A-AB-B} \end{array} + \begin{array}{c} AB_{BA} \\ \text{A-BAB} \end{array} = \begin{array}{c} AB_{\bullet} \\ \text{A-ABABAB} \end{array} + \begin{array}{c} AB_{\epsilon} \\ \text{A-B} \end{array} \quad (\text{neutral, with } \Delta_{\lambda} = -2)$$

$$\begin{array}{c} AB_{AB} \\ \text{A-AB-B} \end{array} + \begin{array}{c} AB_{BA} \\ \text{A-BAB} \end{array} = \begin{array}{c} AB_{\bullet} \\ \text{A-ABABAB} \end{array} + \begin{array}{c} AB_{\epsilon} \\ \text{A-B} \end{array} \quad (\text{neutral, with } \Delta_{\lambda} = -2)$$

$$\begin{array}{c} AB_{AB} \\ \text{A-AB-B} \end{array} + \begin{array}{c} AB_{BA} \\ \text{A-BAB} \end{array} = \begin{array}{c} AB_{\bullet} \\ \text{A-ABABAB} \end{array} + \begin{array}{c} AB_{\epsilon} \\ \text{A-B} \end{array} \quad (\text{neutral, with } \Delta_{\lambda} = -2)$$

$$\begin{array}{c} AB_{AB} \\ \text{A-AB-B} \end{array} + \begin{array}{c} AB_{BA} \\ \text{A-BAB} \end{array} = \begin{array}{c} AB_{\bullet} \\ \text{A-ABABAB} \end{array} + \begin{array}{c} AB_{\epsilon} \\ \text{A-B} \end{array} \quad (\text{neutral, with } \Delta_{\lambda} = -2)$$

Λ	λ
0	0
1	1
2	2
3	2
4	3
5	3
6	4
7	4

DCJ-indel model - Path recombinations

Putting together (examples):

$$\begin{array}{c} \text{AB}_{AB} \\ \text{A-AB-B} \\ 2 \end{array} + \begin{array}{c} \text{AB}_{BA} \\ \text{A-B-A-B} \\ 2 \end{array} = \begin{array}{c} \text{AB}_A \\ \text{A-ABBA-B} \\ 3 \end{array} + \begin{array}{c} \text{AB}_\varepsilon \\ \text{A-B} \\ 1 \end{array} \quad (\text{neutral, with } \Delta_\lambda = -2)$$

(4) (2)

$$\begin{array}{c} \text{AB}_{AB} \\ \text{A-ABAB-B} \\ 4 \end{array} + \begin{array}{c} \text{AB}_{BA} \\ \text{A-B-A-B} \\ 2 \end{array} = \begin{array}{c} \text{AB}_A \\ \text{A-ABABBA-B} \\ 5 \end{array} + \begin{array}{c} \text{AB}_\varepsilon \\ \text{A-B} \\ 1 \end{array} \quad (\text{neutral, with } \Delta_\lambda = -2)$$

(5) (3)

$$\begin{array}{c} \text{AB}_{AB} \\ \text{A-ABAB-B} \\ 4 \end{array} + \begin{array}{c} \text{AB}_{BA} \\ \text{A-BABA-B} \\ 4 \end{array} = \begin{array}{c} \text{AB}_A \\ \text{A-ABABBAABA-B} \\ 7 \end{array} + \begin{array}{c} \text{AB}_\varepsilon \\ \text{A-B} \\ 1 \end{array} \quad (\text{neutral, with } \Delta_\lambda = -2)$$

(6) (4)

Λ	λ
0	0
1	1
2	2
3	2
4	3
5	3
6	4
7	4

DCJ and DCJ-indel models - Capping

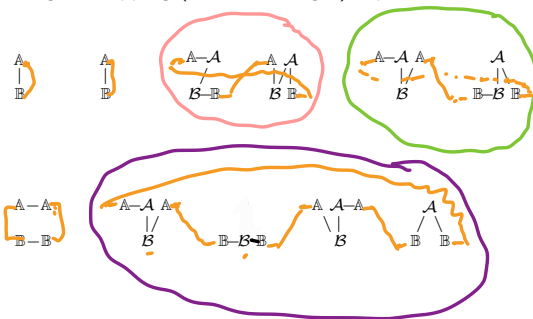
Add caps to close all paths of the graph into cycles, preserving the distance

Canonical capping (no indel edges): maximizes the number of cycles



paths	linking cycle	Δn	Δc	$\Delta(2AB)$	Δ_{DCJ}
AB	(AB)	+0.5	+1	-0.5	0
AA + BB	(AA, BB)	+1	+1	0	0
AA	(AA, Γ_B)	+1	+1	0	0
BB	(BB, Γ_A)	+1	+1	0	0

Singular capping (with indel edges): optimizes the number of cycles and of runs at the same time



paths	linking cycle	Δn	Δc	$\Delta(2AB)$	$\Delta\lambda$	Δ_{DCJ}^λ
$AA_{AB} + BB_{AB}$	(AA_{AB}, BB_{BA})	+1	+1	0	-2	-2
$2 \times AA_{AB} + BB_{BA} + BB_{AB}$	$(AA_{AB}, BB_{BA}, AA_{BA}, BB_{AB})$	+2	+1	0	-4	-3
$AB_{AB} + AB_{BA}$	(AB_{AB}, AB_{BA})	+1	+1	-1	-2	-1
AB	(AB)	+0.5	+1	-0.5	0	0
AA + BB	(AA, BB)	+1	+1	0	0	0